

# Different Resource Management Policies in Multi-Mode Resource Constrained Multi-Project Scheduling

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**Abstract**—This study investigates different resource management policies in resource constrained multi-project problem environments. The problem environment under investigation has alternative modes for activities, a set of renewable and nonrenewable resources used by activities and further considerations like general resource budget. The characterization of the way resources are used by individual projects in the multi-project environment is called resource management policy in this study. The solution approaches in the literature for multi-project problems generally defines the resources as a pool that can be shared by all the projects which in fact creates a general assumption for the resource usage characteristics. This resource management policy is referred as resource sharing policy in this study. Resource sharing policy can be invalid in some certain cases where resource sharing assumption is not feasible because of some characteristics of resources and/or projects which require different resource management policies for the multi-project environment. According to the characteristics of resources and projects, resource management policies such as resource dedication, relaxed resource dedication and generalized resource management policies can be defined. In this paper, these resource management policies will be defined and their mathematical formulations will be presented and discussed.<sup>1</sup>

**Index Terms**—Multi-project scheduling, resource management policies, resource portfolio problem.

## I. INTRODUCTION

Multi-project management constitutes an important part of the business in both manufacturing and services and with its complex nature it is an important research topic in the literature. The multi-project scheduling environment considered in this study consists of several projects that involve finish to start zero time lag and non-preemptive activities. The projects are ready to start at time zero and uncertainty is not considered. The activities have multiple-modes, in other words, they can be executed by choosing one of the available resource usage modes that are manifested as pre-determined resource usage recipes and the corresponding activity durations. The resource set includes both renewable and nonrenewable resources, and their availability is constrained by a general resource budget.

The characterization of the way resources are used by individual projects in the multi-project environment is referred to here as the resource management policy and this type of renewable resources is referred to as the shared resources.

Although the characteristics of the projects and/or resources in a given problem can require different ways of managing the resources, the general approach regarding resource management for the multi-project scheduling problems addressed in the literature has been to consider the available resources as a shared pool which is open to all projects. Under this approach, the individual projects in the multi-project problem can be combined by adding dummy start and finish activities and the overall problem can be solved over this big combined network using single project scheduling methods.

However, the common pool assumption does not hold for several multi-project environments: for example, the projects that are geographically distributed such that the sharing of resources is too costly or infeasible. Such cases require a different resource management policy which is called the resource dedication. Under the resource dedication policy resources are not shared from a common pool but are dedicated to individual projects in certain amounts throughout the planning horizon. The renewable resource that cannot be shared among different projects is called a dedicated resource. A detailed discussion of resource dedication policy in multi-project environments can be found in [1].

The resource dedication policy can be relaxed into another policy by relaxing the time for which the resources are dedicated in the following way: the resources will not be dedicated for the entire planning horizon but for the corresponding project duration. Thus, the renewable resources that are dedicated to a project can be transferred to other projects which have a starting time later than the finish time of the aforementioned project. This resource management policy, referred as the relaxed resource dedication policy can be feasible when resource sharing is not allowed during the course of projects but transferring of renewable resources to another project is possible when one of the projects starts after the other one finishes. This type of renewable resources is

<sup>1</sup>Published in the Proceedings of 2011 World Congress on Engineering and Technology, Vol.2, 64-67, IEEE Press, Beijing, 2011.

called transferrable resources. The final resource management policy discussed in this study is the generalization of the other three. Three types of renewable resources can co-exist in this resource management policy, namely shared resources, dedicated resources and transferrable resources with the corresponding characteristics as described above.

Another aspect of resource management in project scheduling is in regard to the resource availability. While most of the available models assume predetermined or given resource capacities for each resource type in the resource set; these resource availability values can be considered as another set of decisions for the multi-project scheduling problem. Under this approach, the multi-project environment has a conceptually higher decision level which can be defined as deciding the resource capacities according to the project requirements in the multi-project environment. The resource management policies discussed above can be integrated with this general resource capacities decision. This problem is defined as the Resource Portfolio Problem (RPP) which can be modeled in different forms based on the particular resource management policy.

The remainder of this paper continues with detailed discussions and proposed models of shared resources, resource dedication, relaxed resource dedication and generalized resource management policies in RPP. Without loss of generality, the objective for the presented formulations will be the minimization of the total weighted tardiness of the projects.

## II. RESOURCE MANAGEMENT POLICIES

### A. Shared Resources Policy

Resource sharing policy considers the general resource capacities as a shared resource pool where all the individual projects have unlimited access. This point of view for the resource management brings specific advantages for the solution of the multi-project problem. The projects in the multi-project environment can be integrated by adding a general start node that all nodes of the projects that do not have a predecessor are assigned as successors of this start node, and a general end node that all nodes that do not have a successor are assigned as predecessors of this end node. Then this combined project network can be solved using available tools for single project scheduling (see e.g., [5], [2], [6], [3]). For instance, the mathematical formulation given by [7] for the multi-mode resource constrained single project scheduling problem can be used for the resource sharing policy. While this model will not be presented here because of space considerations; it has been used as the base model in developing the formulations for the other two resource management policies.

### B. Resource Dedication Policy

Resource dedication policy in a multi-project environment becomes a requirement when resource cannot be shared among projects because of the characteristics of projects and/or resources. This resource management approach did not attract much attention in the project scheduling literature. Herroelen (2005) identifies different multi-project scheduling environments and specifies resource dedication problem as a tactical

level problem in the case where projects are characterized as independent from each other. [1] investigates resource dedication policy with given general resource capacities and propose solution approaches for the problem.

The mathematical model for RPP with resource dedication policy is given below.

Sets:

$V$	set of projects, $v \in V$
$J_v$	set of activities of project $v$ , $j \in J_v$
$P_v$	set of all precedence relationships of project $v$
$M_{vj}$	set of modes for activity $j$ of project $v$ , $m \in M_{vj}$
$K$	set of renewable resources, $k \in K$
$I$	set of nonrenewable resources, $i \in I$
$T$	set of time periods, $t \in T$

Parameters:

$E_{vj}$	Earliest finish time of activity $j$ of project $v$
$L_{vj}$	Latest finish time of activity $j$ of project $v$
$d_{vjm}$	Duration of activity $j$ , operating on mode $m$
$r_{vjkm}$	Renewable resource $k$ usage of activity $j$ of project $v$ , operating on mode $m$
$w_{vjim}$	Nonrenewable resource $i$ usage of activity $j$ of project $v$ , operating on mode $m$
$dd_v$	Assigned due date for project $v$
$c_v$	Relative weight of project $v$
$cr_k$	Unit cost of renewable resource $k$
$cw_i$	Unit cost of nonrenewable resource $i$
$tb$	Total resource budget

Decision Variables:

$x_{vjmt}$	=	$\begin{cases} 1 & \text{if activity } j, \text{ operating on mode } m, \\ & \text{in project } v \text{ is finished at period } t \\ 0 & \text{otherwise} \end{cases}$
$BR_{vk}$	=	Amount of renewable resource $k$ dedicated to project $v$
$BW_{vi}$	=	Amount of nonrenewable resource $i$ dedicated to project $v$
$TC_v$	=	Weighted tardiness cost of project $v$
$R_k$	=	Total amount of required renewable resource $k$
$W_i$	=	Total amount of required nonrenewable resource $i$

Mathematical Model RPP-RD

$$\min. z = \sum_{v \in V} TC_v \quad (1)$$

Subject to

$$\sum_{m \in M_{vj}} \sum_{t=E_{vj}}^{L_{jv}} x_{vjmt} = 1 \quad \forall j \in N_v \text{ and } \forall v \in V \quad (2)$$

$$\sum_{m \in M_{vj}} \sum_{t=E_{vb}}^{L_{vb}} (t - d_{vbm}) x_{vbm} \geq \sum_{m \in M_{vj}} \sum_{t=E_{va}}^{L_{va}} t x_{vam} \quad \forall (a, b) \in P \text{ and } \forall v \in V \quad (3)$$

$$\sum_{j \in N_v} \sum_{m \in M_{vj}} \sum_{q=t}^{t+d_{vjm}-1} r_{vjkm} x_{vjmq} \leq BR_{vk} \quad \forall k \in K \quad \forall t \in T \quad \forall v \in V \quad (4)$$

$$\sum_{j \in N_v} \sum_{m \in M_{vj}} \sum_{t=E_{vj}}^{L_{vj}} w_{vjim} x_{vjmt} \leq BW_{vi} \quad \forall i \in I \quad \text{and} \quad \forall v \in V \quad (5)$$

$$\sum_{v \in V} BR_{vk} \leq R_k \quad \forall k \in K \quad (6)$$

$$\sum_{v \in V} BW_{vi} \leq W_i \quad \forall i \in I \quad (7)$$

$$\sum_{i \in I} c w_i W_i + \sum_{v \in V} c r_k R_k \leq t b \quad (8)$$

$$TC_v \geq c_v \left( \sum_{t=E_{vN}}^{L_{vN}} \sum_{m \in M_{vN}} x_{vNmt} - dd_v \right) \quad \forall v \in V \quad (9)$$

$$x_{vjmt} \in \{0, 1\} \quad \forall j \in J, \quad \forall t \in T, \quad \forall m \in M \quad \text{and} \quad \forall v \in V \quad (10)$$

$$BR_{vk} \in Z^+ \quad \forall v \in V \quad \text{and} \quad \forall k \in K \quad (11)$$

$$BW_{vi} \in Z^+ \quad \forall v \in V \quad \text{and} \quad \forall i \in I \quad (12)$$

$$R_k \in Z^+ \quad \forall k \in K \quad (13)$$

$$W_i \in Z^+ \quad \forall i \in I \quad (14)$$

$$TC_v \in Z^+ \quad \forall v \in V \quad (15)$$

The objective function (1) is determined as minimization of the total weighted tardiness cost for all projects. Constraint set (2) forces all the activities of all the projects to finish once and only once. Constraint set (3) satisfies the precedence relations between activities. Constraint sets (4) and (5) set the renewable and nonrenewable resource dedication values for each project respectively. Constraint sets (6) and (7) calculate the total renewable and nonrenewable resource requirements respectively. Constraint (8) limits the total renewable and nonrenewable resource costs with the general resource budget. And finally constraint set (9) calculates the weighted tardiness values for each project.

The resource dedication concept is achieved by constraint sets (4) and (6). Constraint set (4) sets  $BR_{vk}$  for the corresponding resource and project as the maximum resource usage over all time periods which is the required amount of resource  $k$  that must be dedicated to project  $v$ . Constraint set (6) ensures that the resource dedication values for all projects cannot exceed the general renewable resource capacity. Under this approach renewable resources cannot be shared among different projects.

### C. Relaxed Resource Dedication Policy

The pure resource dedication policy is not a very general case even though it has its own merits of usage. In some cases, the renewable resources that are dedicated to an already

finished project can be used by the projects that are subject to start. This approach would have certain benefits when renewable resources can be transferred in this way and the resource budget is limited.

Mathematical model for RPP under relaxed resource dedication policy is given below.

*Additional Parameters:*

$\Omega$  A big number

*Additional Decision Variables:*

$f_v$  = Release time of project  $v$

$S_{vv'k}$  = Amount of renewable resource  $k$  given to project  $v'$  from project  $v$

$y_{vv'}$  =  $\begin{cases} 1 & \text{if project } v' \text{ is released after project } \\ & v \text{ is finished} \\ 0 & \text{otherwise} \end{cases}$

*Model RPP-RRD*

$$\min. z = \sum_{v \in V} TC_v \quad (1)$$

Subject to

$$\sum_{j \in N_v} \sum_{m \in M_{vj}} \sum_{q=t}^{t+d_{vjm}-1} r_{vjkm} x_{vjmq} \leq BR_{vk} + \sum_{v' \in V} SR_{v'vk} \quad \forall k \in K \quad \forall t \in T \quad \forall v \in V \quad (16)$$

$$BR_{vk} + \sum_{v' \in V} SR_{v'vk} \geq \sum_{v' \in V} SR_{vv'k} \quad \forall k \in K \quad \text{and} \quad \forall v \in V \quad (17)$$

$$f_{v'} - f_v - \sum_{t=E_{vN}}^{L_{vN}} \sum_{m \in M_{vN}} t x_{vNmt} \leq \Omega(y_{vv'}) \quad \forall v, v' \in V \quad (18)$$

$$f_v + \sum_{t=E_{vN}}^{L_{vN}} \sum_{m \in M_{vN}} t x_{vNmt} - f_{v'} \leq \Omega(1 - y_{vv'}) \quad \forall v, v' \in V \quad (19)$$

$$SR_{vv'k} \leq \Omega(y_{vv'}) \quad \forall v, v' \in V \quad \text{and} \quad \forall k \in K \quad (20)$$

$$TC_v \geq C_v \left( f_v + \sum_{t=E_{vN}}^{L_{vN}} \sum_{m \in M_{vN}} x_{vNmt} - dd_v \right) \quad \forall v \in V \quad (21)$$

$$y_{vv'} \in \{0, 1\} \quad \forall v \in V \quad (22)$$

$$f_v \in Z^+ \quad \forall v, v' \in V \quad (23)$$

$$SR_{vv'k} \in Z^+ \quad \forall v, v' \in V \quad (24)$$

$$(2), (3), (5), (7), (8), (10), (11), (12), (13), (14), (15)$$

The resource sharing policy that allows resource transfer between projects results in the following changes to the mathematical model. First of all, renewable resource usage constraints for each project (16) have a resource usage capacity

as the sum of dedicated resource value and the total transferred resource to the project from the other projects. In constraint (17), the total resource that can be transferred by a project is limited with the total resource dedicated to this project and the total resource it gained from transfers. Constraint sets (18) and (19) sets decision variable  $y_{vv'}$  to 1 if project  $v$  is finished before project  $v'$  is released and 0 otherwise. Thus the  $SR_{vv'k}$  values will only have positive values if project  $v$  is finished before project  $v'$  is released with constraint (20), it will be set to 0 otherwise. The weighted tardiness for each project is calculated according to the release times of project in constraint set (21).

#### D. Generalized Resource Management Policy

The generalized resource management policy incorporates all the characteristics of the aforementioned resource management policies by identifying three different types of renewable resources: shared, dedicated and transferable. The mathematical formulation for this resource management policy will have three different types of renewable resource usage constraints for different renewable resource types. For the corresponding renewable resource types different renewable resource usage and general renewable resource capacity constraints can be used for the mathematical formulation of the generalized resource management policy.

### III. CONCLUSION

To realistically model different multi-project environments, different resource management policies should be taken into account. In this study, different resource management policies are characterized as the shared resources policy, resource dedication policy, relaxed resource dedication policy and the generalization of these three. The mathematical formulations for the resource dedication and relaxed resource dedication policies are developed and discussed in a multi-project scheduling environment with a general resource budget. Solution methodologies for the models under different resource management policies will require different approaches because of the characteristics that resource management policies impose on the problem environment.

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